



IN THE CLAIMS

Please amend the claims as follows:

Claims 1-8 (Canceled).

Claim 9 (Currently Amended): A barrel grasping and lifting device according to claim ~~[[8]]~~ 15, wherein the grasp system ~~for grasping~~ is suspended from a column, the at least one moveable arm is suspended from a plate sliding along the column, and an elevator system adjusts the height of the plate of the column.

Claim 10 (Previously Presented): A barrel grasping and lifting device according to claim 9, wherein the plate comprises a carriage configured to slide radially, and from which the at least one moveable arm is suspended, and a carriage slide control.

Claim 11 (Currently Amended): A barrel grasping and lifting device according to claim 10, wherein the carriage comprises means for rotating the finger of the movable arm, said means for rotating comprising a rod located on the arm, ~~and wherein the finger is lifted while rotating on the at least one moveable arm and is connected to the means for rotating by a rod located on the at least one moveable arm.~~

Claim 12 (Currently Amended): A barrel grasping and lifting device according to claim ~~[[8]]~~ 15, further comprising ~~wherein the system for grasping comprises a support, at least one suction cap, and a ball and socket for mounting [[the]]~~ said suction cap ~~onto the to~~ said support.

Claim 13 (Currently Amended): A barrel grasping and lifting device according to claim [[8]] 15, further comprising means for inspecting the barrel.

Claim 14 (Currently Amended): A barrel grasping and lifting device according to claim 13, wherein the means for inspecting the barrel comprises means located on the at least one moveable arm, and means located within the grasp system ~~for grasping~~.

Claim 15 (New): A barrel grasping and lifting device, the barrel being substantially cylindrical and comprising a lower surface, an upper surface and a peripheral surface, the device comprising:

a group system for grasping the upper surface of the barrel, at least one moveable arm and a centering mechanism,

the grasp system includes a support, and at least one suction cup mounted under the support for sucking the upper surface,

the centering mechanism being mounted on said support and comprising fingers that can be extended radially,

the movable arm being vertical and vertically slidable with respect to the support alongside the peripheral surface, and comprising a finger at a lower end of the arm, and

means for moving said finger under the lower surface.